

Introduction to DirectX Raytracing: Overview and Introduction to Ray Tracing Shaders

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More information: <u>http://intro-to-dxr.cwyman.org</u>



Next Steps



- Pete gave a nice overview of basics:
 - What is ray tracing? Why use ray tracing?
- Now we want to ask:
 - How do I do it?



Next Steps

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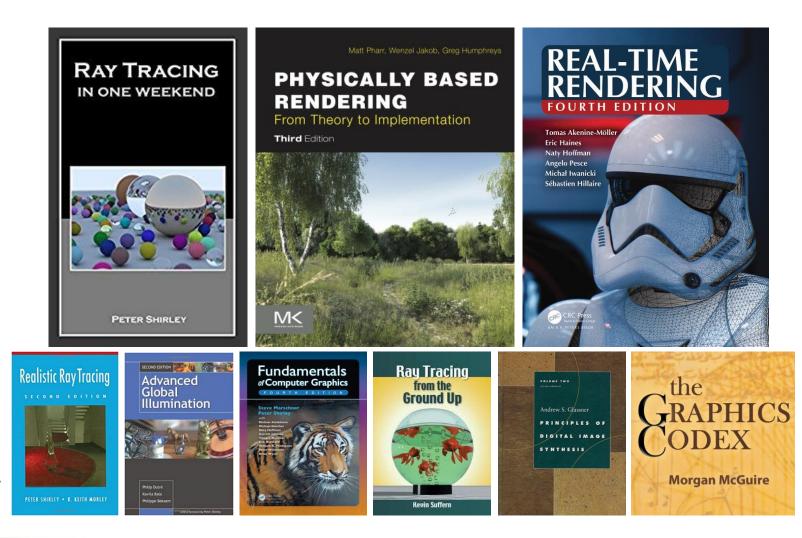
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 - What is ray tracing? Why use ray tracing?
- Now we want to ask:
 - How do I do it?
- Of course, you could start from scratch:
 - Write a CPU ray tracer; plenty of resources
 - Write a GPU ray tracer; can be tricky & ugly



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- Pete gave a nice overview of basics:
 - What is ray tracing? Why use ray tracing?
- Now we want to ask:
 - How do I do it?
- Of course, you could start from scratch:
 - Write a CPU ray tracer; plenty of resources
 - Write a GPU ray tracer; can be tricky & ugly
- Use vendor-specific APIs
 - Hide ugly, low-level implementation details
 - Poor scaling cross-vendor, interact w / raster



Use Standardized API: DirectX Raytracing



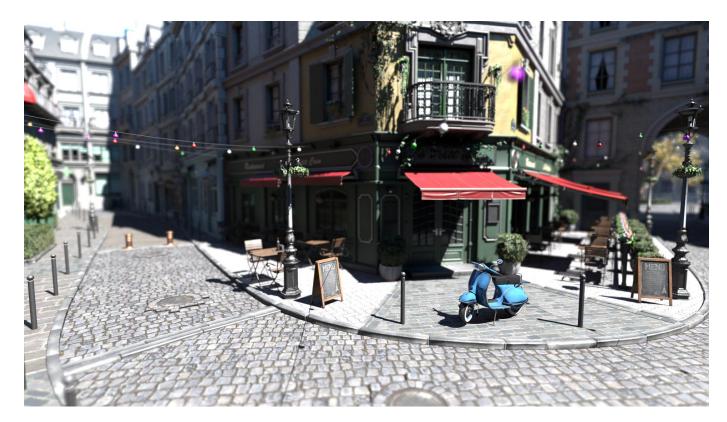
- Of course, that's why you are here:
 - Today's goal: show how to use DX Raytracing



Use Standardized API: DirectX Raytracing

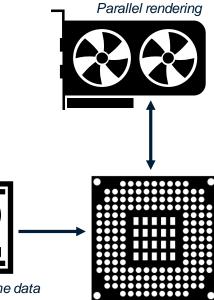


- Of course, that's why you are here:
 - Today's goal: show how to use DX Raytracing
- Part of a widely-used API, DirectX
- Shares resources:
 - No data copying between raster and ray tracing
- Works across multiple vendors, either:
 - Via vendor-provided software or hardware
 - Via standardized compatibility layer (on DX12 GPUs)





• Two main parts:



Resource management Spawn parallel GPU work GPU pass management High-level rendering algorithms

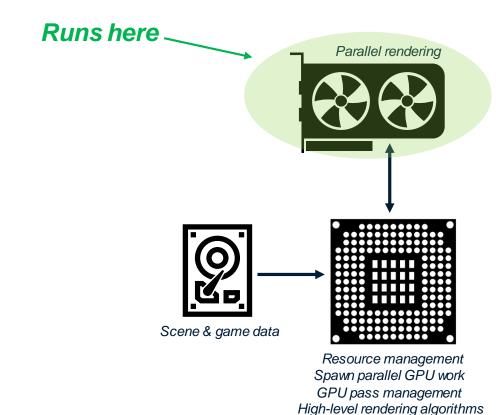
Scene & game data

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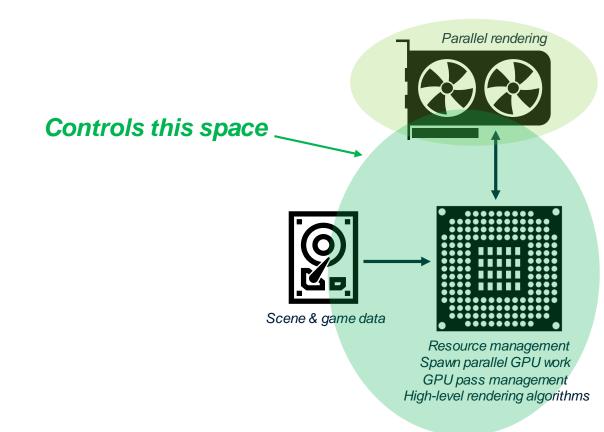


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 - Includes parallel rendering and other parallel tasks
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 - CPU host code (often "DirectX API"):
 - Manages memory resources (disk \rightarrow CPU \leftrightarrow GPU)
 - · Sets up, controls, manages, spawns GPU tasks
 - Defines shared graphics data structures (like ray accelerations structures)
 - Allows higher-level graphics algorithms requiring multiple passes

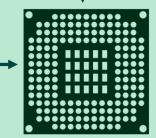




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This rest of this talk focuses on _____ DirectX Raytracing shaders! Parallel rendering



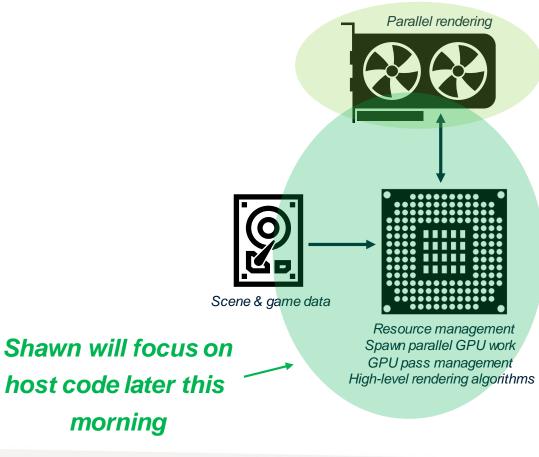


Scene & game data

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- Typically written in a C-like high-level language
 - In DirectX, shaders are written in the High Level Shading Language (HLSL)

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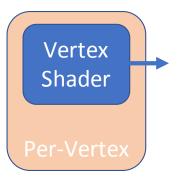
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 - In DirectX, shaders are written in the High Level Shading Language (HLSL)
- Individual shaders can represent instructions for complete GPU tasks
 - E.g., DirectX's compute shaders
- Or they can represent a subset of a more complex pipeline
 - E.g., transforming geometry to cover the right pixels in DirectX's vertex shaders

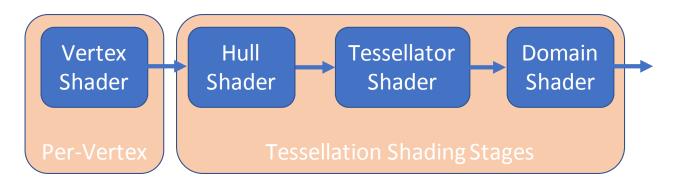






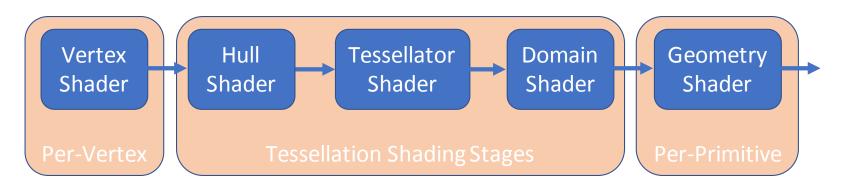
- Run a shader, the vertex shader, on each vertex sent to the graphics card
 - This usually transforms it to the right location relative to the camera





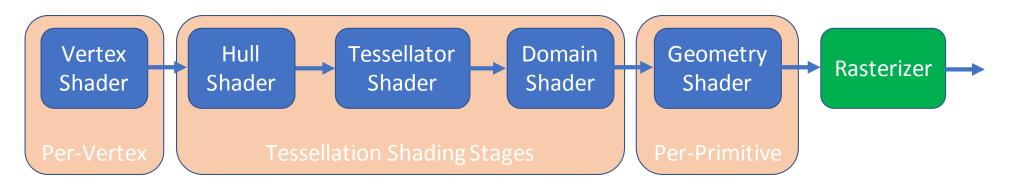
- Group vertices into triangles, then run tessellation shaders to allow GPU subdivision of geometry
 - Includes 3 shaders with different goals, the *hull shader*, *tessellator shader*, and *domain shader*





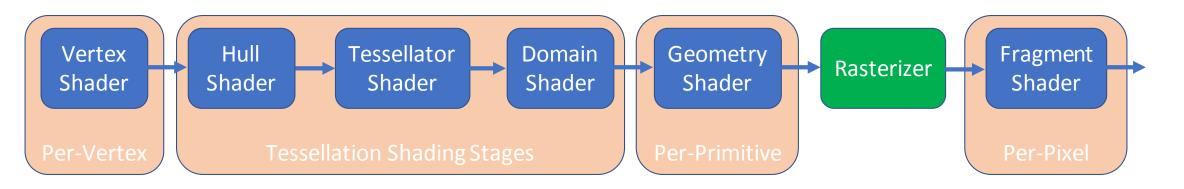
- Run a shader, the *geometry shader*, on each tessellated triangle
 - Allows computations that need to occur on a complete triangle, e.g., finding the geometric surface normal





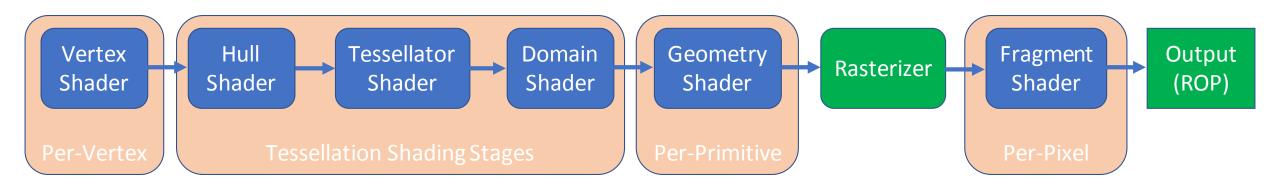
- Rasterize our triangles (i.e., determine the pixels they cover)
 - Done by special-purpose hardware rather than user-software
 - Only a few developer controllable settings





- Run a shader, the *pixel shader* (or *fragment shader*), on each pixel generated by rasterization
 - This usually computes the surface's color

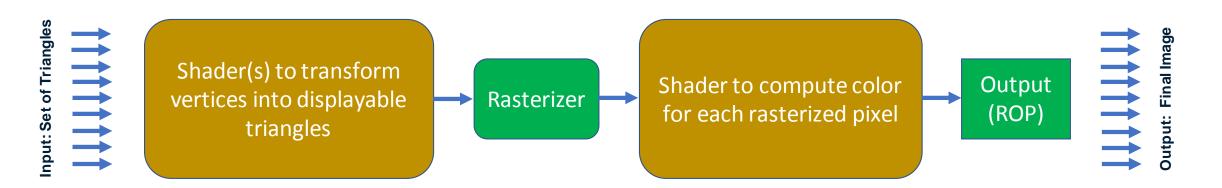




- Merge each pixel into the final output image (e.g., doing blending)
 - Usually done with special-purpose hardware
 - Hides optimizations like memory compression and converting image formats



• Squint a bit, and that pipeline looks like:

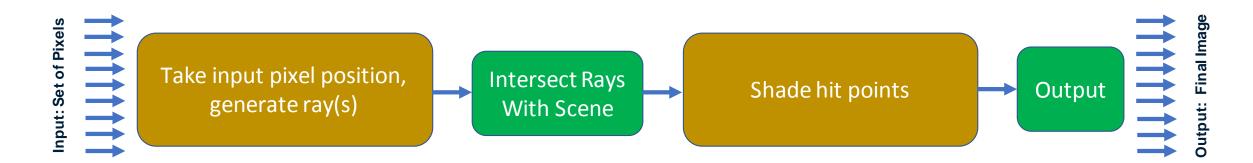




• So what might a simplified ray tracing pipeline look like?

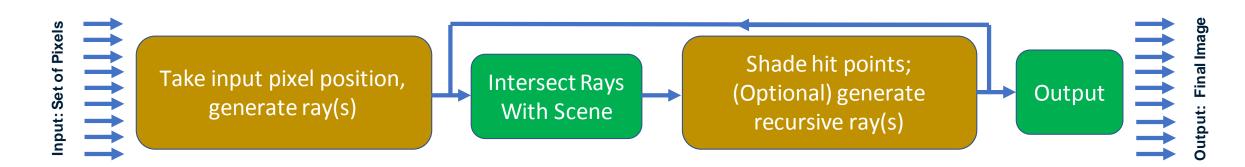


• So what might a simplified ray tracing pipeline look like?



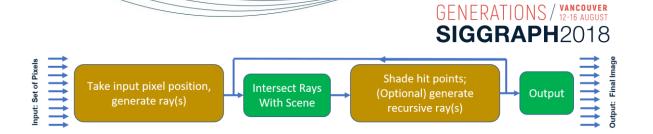


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- One advantage of ray tracing:
 - Algorithmically, much easier to add recursion

Please note: A very simplified representation



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Runs once per algorithm (or per pass)

Intersect Rays

With Scene

Input: Set of Pixels

Take input pixel position,

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Output

(Optional) generate

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Defines geometric shapes, widely reusable

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- Pipeline is split into *five* new shaders:
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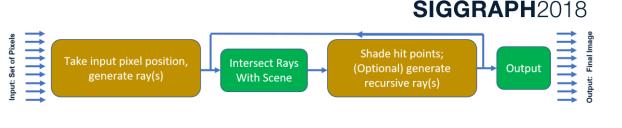
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Siggraph2018 Take input pixel position, generate ray(s) Take input pixel position, generate ray(s) Shade hit points; (Optional) generate recursive ray(s)

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- Runs once per algorithm (or per pass)
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Runs once per algorithm (or per pass) Defines geometric shapes, widely reusable

¹Note: Read spec for more advanced usage, since meaning of "any" may not match your expectations

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Runs once per algorithm (or per pass) Defines geometric shapes, widely reusable Defines behavior of ray(s) Different between shadow, primary, indirect rays

Intersect Ravs

With Scene

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generate ray(s)

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Outpu

(Optional) generate

recursive ray(s)

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 - Any-hit¹ shader(s) run once per hit (e.g., to determine transparency)
- An new, unrelated *sixth* shader:
 - A callable shader can be launched from another shader stage

Runs once per algorithm (or per pass)
 Defines geometric shapes, widely reusable
 Defines behavior of ray(s)
 Different between shadow, primary, indirect rays

Intersect Ravs

With Scene

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Take input pixel position,

generate ray(s)

Abstraction allows this; explicitly expose it (Due to time limitations, see DXR spec for further details)

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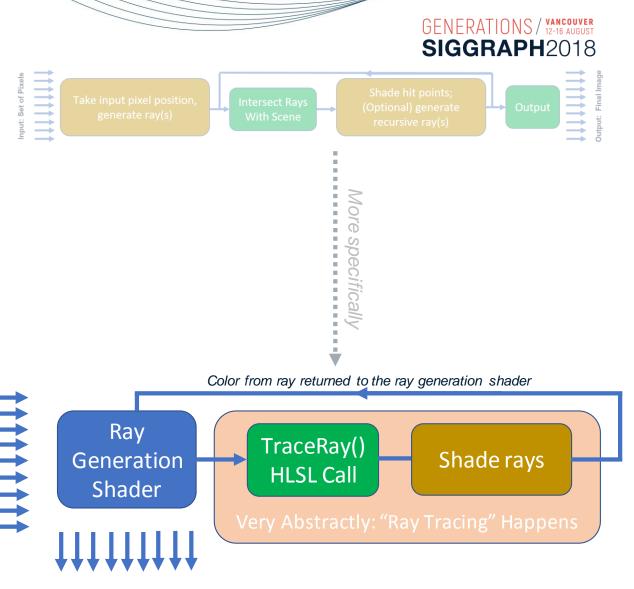
Shade hit points;

(Optional) generate

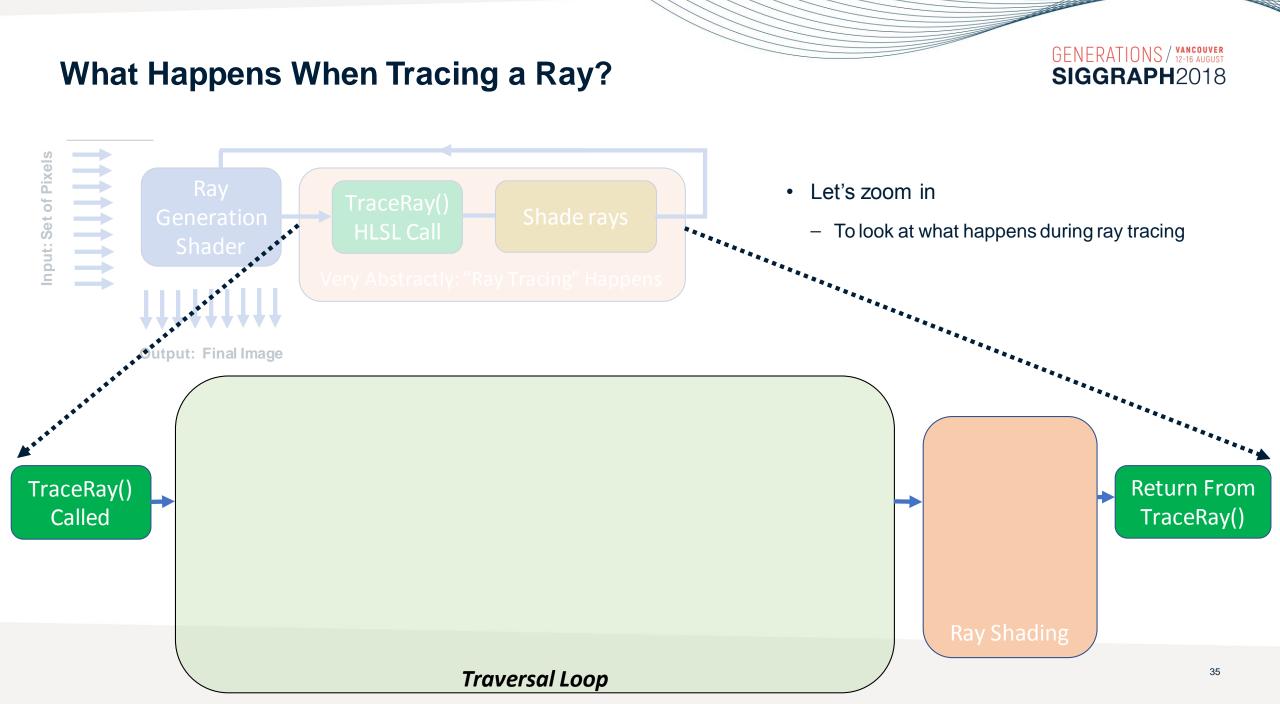
recursive ray(s)

Ray Generation Shader

- Write code to:
 - Specify what ray(s) to trace for each pixel
- In particular:
 - Launch ray(s) by calling new HLSL TraceRay() intrinsic
 - Accumulate ray color into image after ray tracing finishes



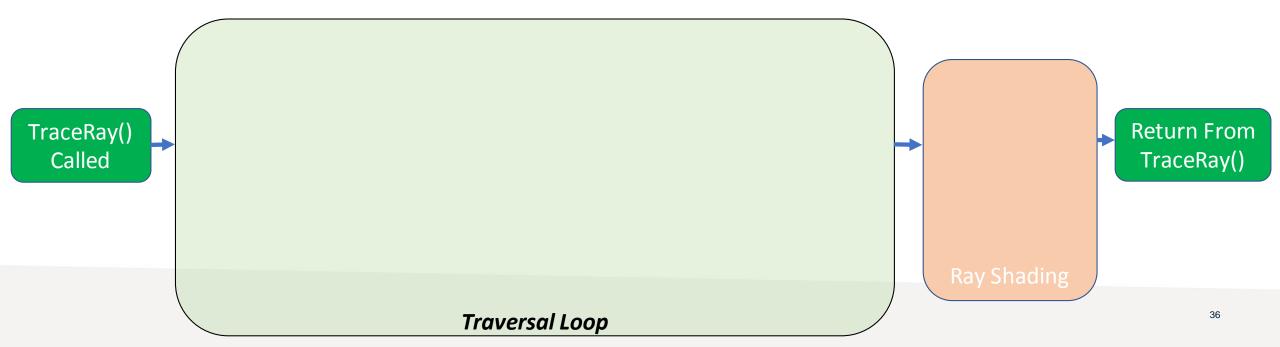
Input: Set of Pixels



What Happens When Tracing a Ray?



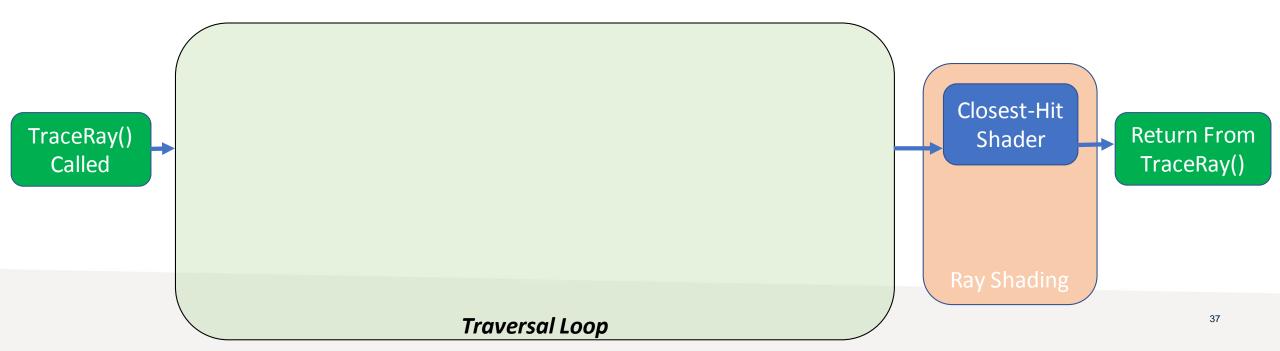
- A good mental model:
 - First, we traverse our scene to find what geometry our ray hits



What Happens When Tracing a Ray?



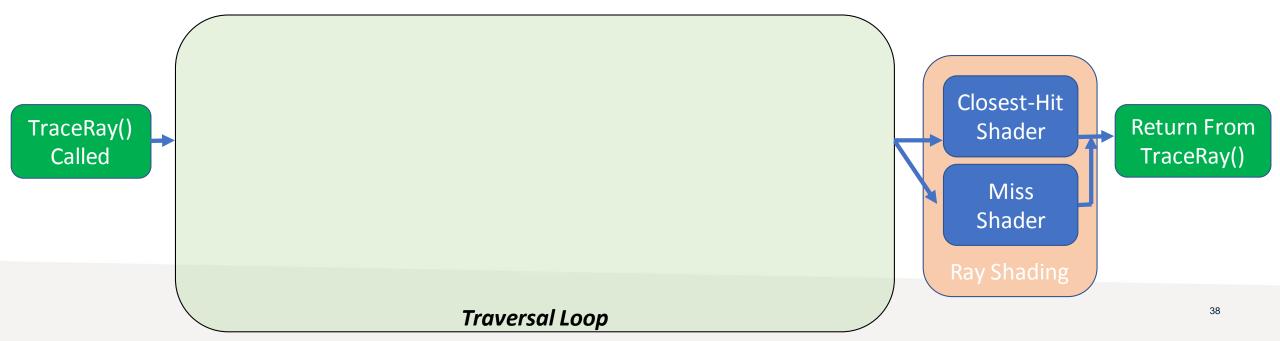
- A good mental model:
 - First, we traverse our scene to find what geometry our ray hits
 - When we find the closest hit, shade at that point using the **closest-hit shader**
 - This shader is a ray property; in theory, each ray can have a different closest-hit shader.



What Happens When Tracing a Ray?

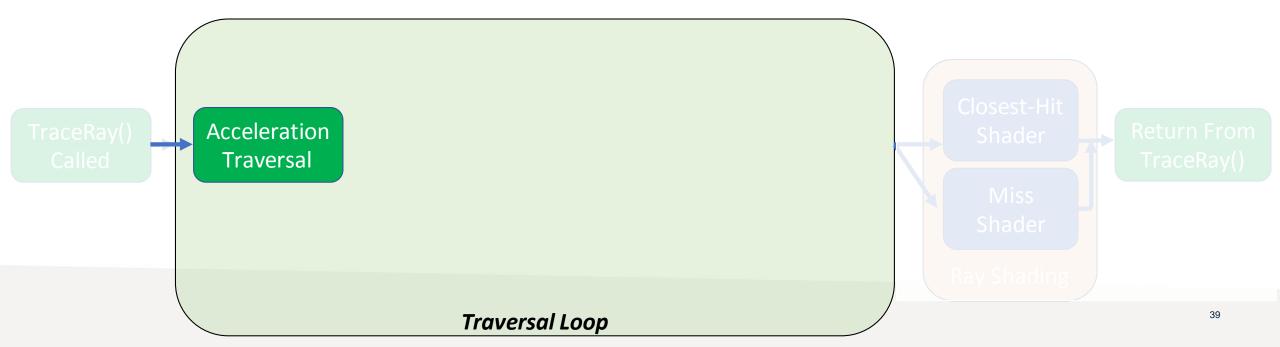


- If our ray misses all geometry, the miss shader gets invoked
 - Can consider this a shading routine that runs when you see the background
 - Again, the miss shader is specified per-ray



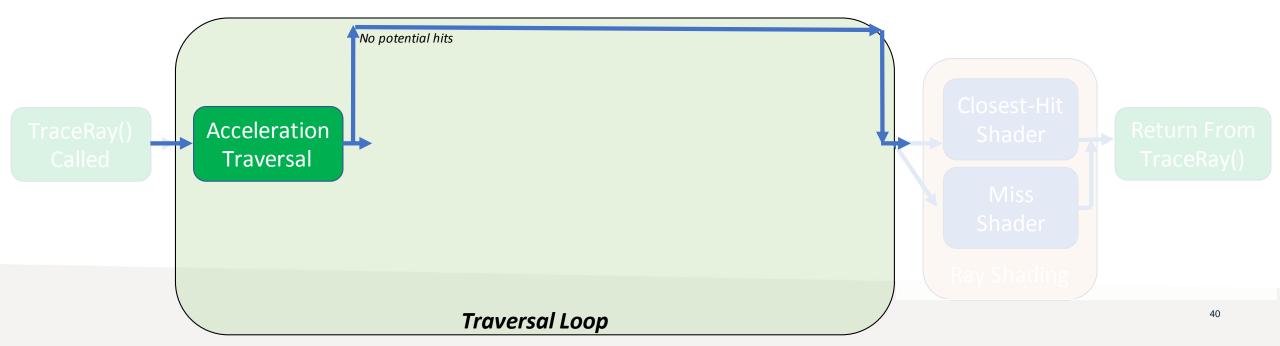


- Traverse the scene acceleration structure to ignore trivially-rejected geometry
 - An opaque process, with a few developer controls
 - Allows vendor-specific algorithms and updates without changing render code



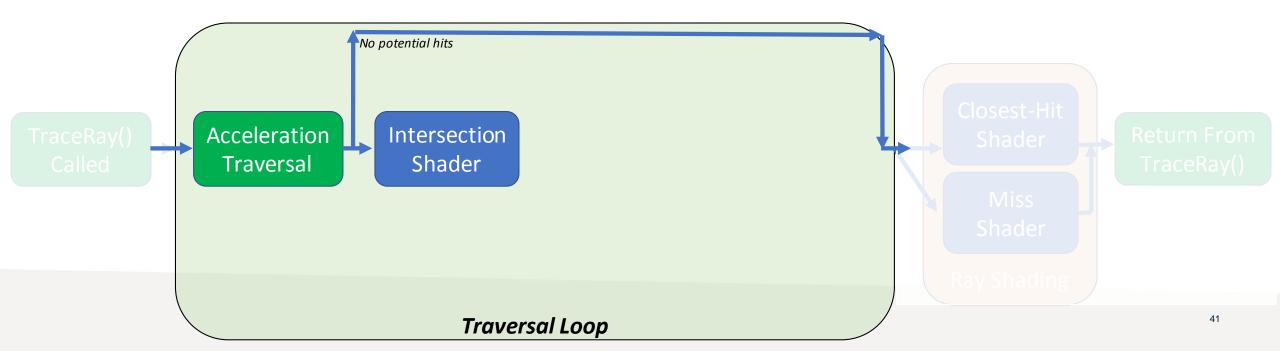


• If all geometry trivially ignored, ray traversal ends



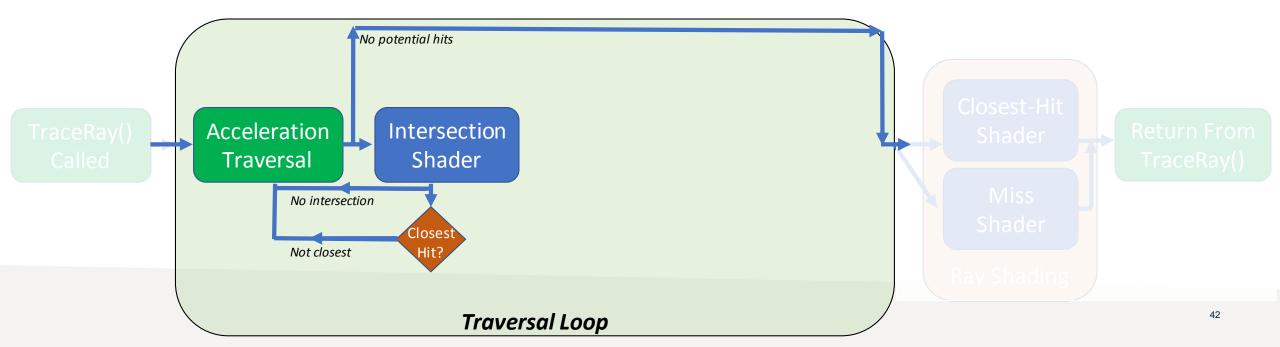


- If all geometry trivially ignored, ray traversal ends
- For potential intersections, an intersection shader is invoked
 - Specific to a particular geometry type (e.g., one shader for spheres, one for Bezier patches)
 - DirectX includes a default, optimized intersection for triangles





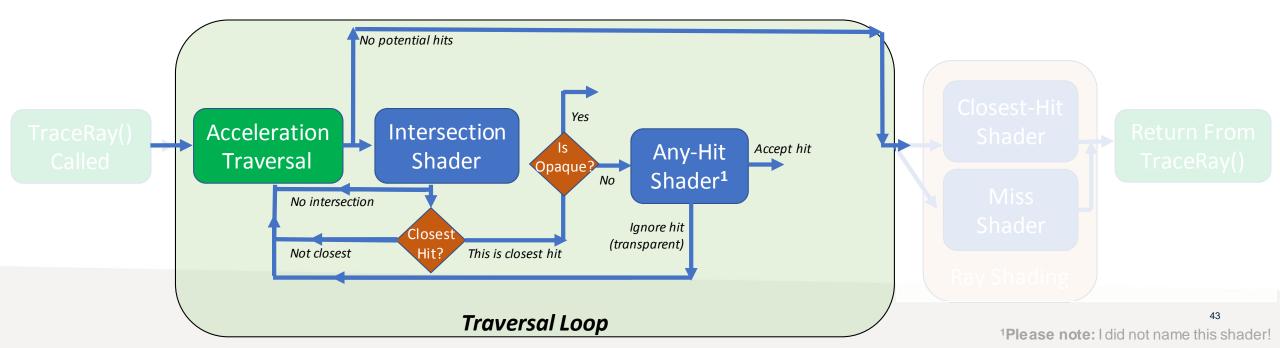
- No shader-detected intersection? Detected intersection not the closest hit so far?
 - Continue traversing through our scene





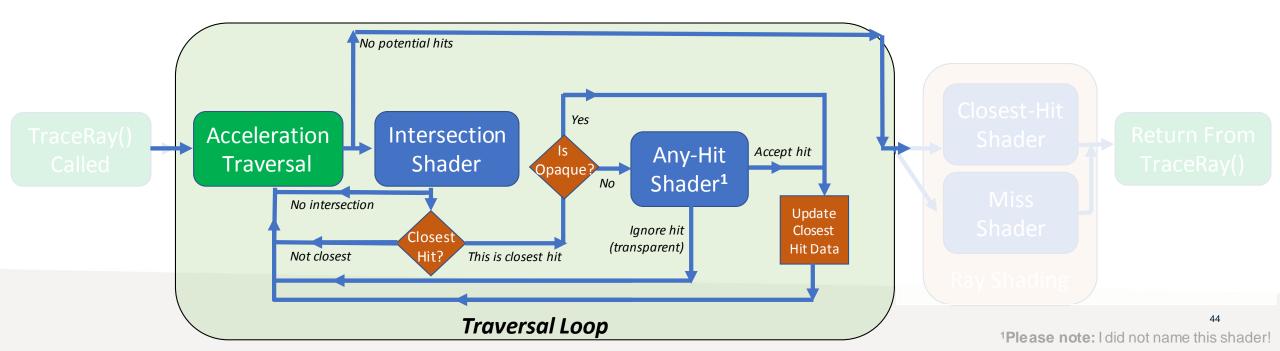
• Detected hit might be transparent? Run the any-hit shader1

- A ray-specific shader, specified in conjunction with the closest-hit shader
- Shader can call IgnoreHit() to continue traversing, ignoring this surface





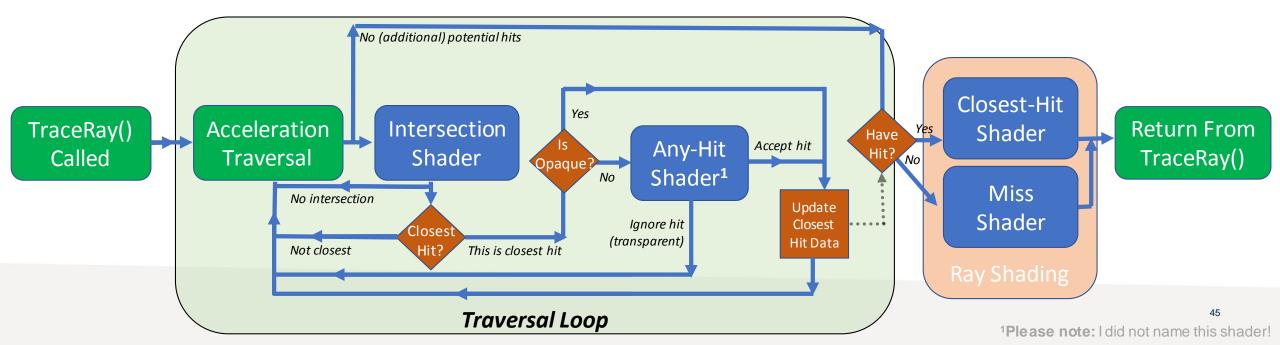
- Update the closest hit point with newly discovered hit
- Continue traversing to look for closer intersections



Ray Traversal Pipeline

• Continue traversing scene until no closer hits discovered

- Had a valid hit along the ray? Shade via the closest-hit shader
- No valid hits? Shade via the miss shader



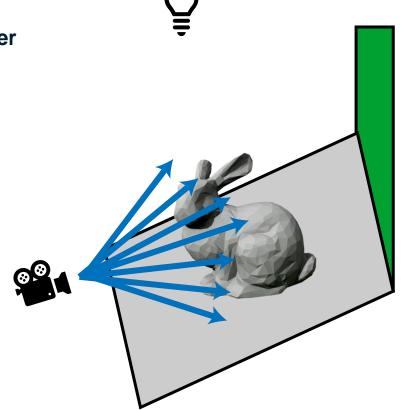
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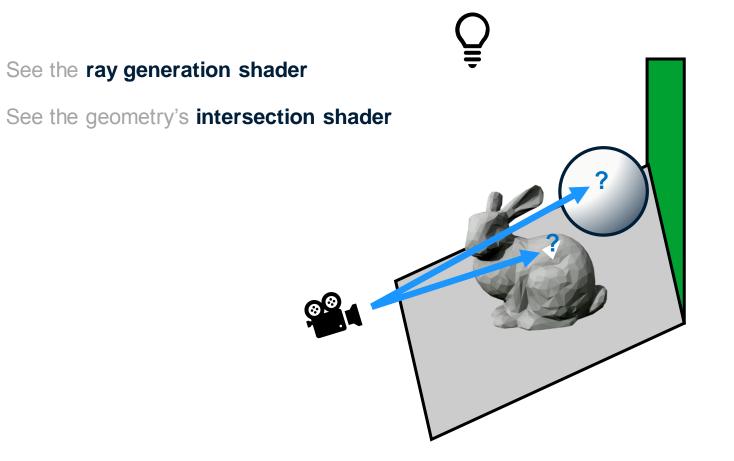
• Control where your rays start?





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- Control where your rays start?
- Control when your rays intersect geometry?



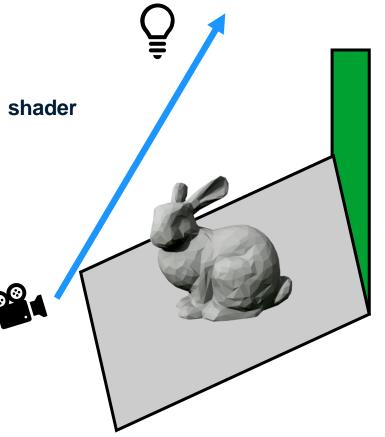


- Control where your rays start?
- Control when your rays intersect geometry?
- Control what happens when rays miss?

See the ray generation shader

See the geometry's intersection shader

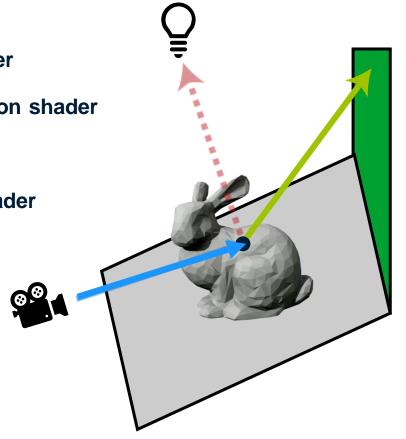
See your ray's miss shader





- Control where your rays start?
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- Control what happens when rays miss?
- Control how to shade your final hit points?

- See the ray generation shader
- See the geometry's intersection shader
- See your ray's miss shader
- See your ray's closest-hit shader





- Control where your rays start?
- Control when your rays intersect geometry?
- Control what happens when rays miss?
- Control how to shade your final hit points?
- Control how transparency behaves?

See the ray generation shader

See the geometry's intersection shader

See your ray's miss shader

See your ray's closest-hit shader

See your ray's any-hit shader



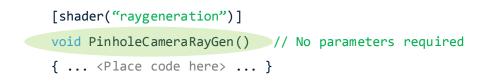
What Goes Into a DirectX Ray Tracing Shader?

More information: <u>http://intro-to-dxr.cwyman.org</u>



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 - Think main() in C/C++





- As any program, need an entry point where execution starts
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- Shader entry points can be arbitrarily named



[shader("raygeneration")]

void PinholeCameraRayGen()

// No parameters required

{ ... <Place code here> ... }

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- Type specified by HLSL attribute: [shader("shader-type")]
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[shader("anyhit")]
void RayAnyHit(inout RayPayload data,
              IntersectAttribs attribs)
{ ... <Place code here> ... }
[shader("closesthit")]
void RayClosestHit(inout RayPayload data,
                  IntersectAttribs attribs)
{ ... <Place code here> ... }
```

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 - **IntersectAttribs** has data reported on hits (by intersection shader)

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- Ray payload is an arbitrary user-defined, user-named structure
 - Contains intermediate data needed during ray tracing

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{				
<pre>float3 rayColor;</pre>				
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Not familiar with HLSL?

Built-in types include scalar types: **bool**, **int**, **uint**, **float** Also vectors of up to 4 components: **bool1**, **int2**, **uint3**, **float4** And matrices up to 4x4 size: **uint1x4**, **float2x2**, **int3x2**, **float4x4**

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- Ray payload is an arbitrary user-defined, user-named structure
 - Contains intermediate data needed during ray tracing
 - Note: Keep ray payload as small as possible
 - Large payloads will reduce performance; spill registers into memory

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struct SimpleRayPayload
{
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};
```

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 - Contains intermediate data needed during ray tracing
 - Note: Keep ray payload as small as possible
 - Large payloads will reduce performance; spill registers into memory

• A simple ray might look like this:

- Sets color to blue when the ray misses
- Sets color to red when the ray hits an object

```
struct SimpleRayPayload
{
    float3 rayColor;
};
```



- Communications intersection information needed for shading
 - E.g., how do you look up textures for your primitive?



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• Specific to each intersection type

- One structure for triangles, one for spheres, one for Bezier patches



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 - One structure for triangles, one for spheres, one for Bezier patches
 - DirectX provides a built-in for the fixed function triangle intersector

struct	BuiltinIntersectionAttribs	

{ // Barycentric coordinates of hit in
 float2 barycentrics; // the triangle are: (1-x-y, x, y)
}



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- One structure for triangles, one for spheres, one for Bezier patches
- DirectX provides a built-in for the fixed function triangle intersector
- Could imagine custom intersection attribute structures like:

struct BuiltinIntersectionAttribs

```
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}
```

struct PossibleSphereAttribs

{	<pre>// Giving (theta,phi) of the hit on</pre>			
float2 thetaPhi;	<pre>// the sphere (thetaPhi.x, thetaPhi.y)</pre>			
}				
struct PossibleVolumeAttribs				
{ // D	Ooing volumetric ray marching? Maybe			
float3 vox; // r	<pre>return voxel coord: (vox.x, vox.y, vox.z)</pre>			
}				



· Communications intersection information needed for shading

- E.g., how do you look up textures for your primitive?

· Specific to each intersection type

- One structure for triangles, one for spheres, one for Bezier patches
- DirectX provides a built-in for the fixed function triangle intersector
- Could imagine custom intersection attribute structures like:
- Limited attribute structure size: max 32 bytes

struct BuiltinIntersectionAttribs

```
{ // Barycentric coordinates of hit in
  float2 barycentrics; // the triangle are: (1-x-y, x, y)
}
```

struct PossibleSphereAttribs

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	float3 vox; //	return voxel coord: (vox.x, vox.y, vox.z)		
3				

A Simple Example



A Simple Example



• Besides our shader, what data is needed on the GPU to shoot rays?



- Besides our shader, what data is needed on the GPU to shoot rays?
- We need somewhere to write our output

// A standard DirectX unordered access view (a.k.a., "read-write texture")
RWTexture<float4> outTex;



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- Where are we looking? We need camera data

// A standard DirectX unordered access view (a.k.a., "read-write texture")
RWTexture<float4> outTex;

```
// An HLSL "constant buffer", to be populated from your host C++ code
cbuffer RayGenData {
```

```
float3 wsCamPos; // World space camera position
float3 wsCamU, wsCamV, wsCamW; // Camera right, up, and forward vectors
```

};



- · Besides our shader, what data is needed on the GPU to shoot rays?
- We need somewhere to write our output
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- Need to know about our scene geometry

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cbuffer RayGenData {
    float3 wsCamPos; // World space camera position
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```

```
// Our scene's ray acceleration structure, setup via the C++ DirectX API
RaytracingAccelerationStructure sceneAccelStruct;
```



- · Besides our shader, what data is needed on the GPU to shoot rays?
- We need somewhere to write our output
- Where are we looking? We need camera data
- Need to know about our scene geometry
- Also need information on how to shade the scene
 - More complex topic
 - Depends on your program's or engine's material format
 - Depends on your shading models
 - Leave for later, see full tutorial code for examples

// A standard DirectX unordered access view (a.k.a., "read-write texture")
RWTexture<float4> outTex;

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// An HLSL "constant buffer", to be populated from your host C++ code
cbuffer RayGenData {
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RWTexture<float4> outTex; // Output texture cbuffer RayGenData { // World-space camera data $CPU \rightarrow GPU$ data declarations float3 wsCamPos; float3 wsCamU, wsCamV, wsCamW; }; RaytracingAccelerationStructure sceneAccelStruct;

void PinholeCamera() {

. . .

}

```
= DispatchRaysIndex().xy;
uint2 curPixel
```

```
uint2 totalPixels = DispatchRaysDimensions().xy;
```

What pixel are we currently computing? How many rays, in total, are we generating?

. . .

[shader("raygeneration")]
void PinholeCamera() {
 uint2 curPixel = DispatchRaysIndex().xy;
 uint2 totalPixels = DispatchRaysDimensions().xy;
 float2 pixelCenter = (curPixel + float2(0.5,0.5)) / totalPixels;
 float2 ndc = float2(2,-2) * pixelCenter + float2(-1,1);
 float3 pixelRayDir = ndc.x * wsCamU + ndc.y * wsCamV + wsCamZ;



RWTexture <float4> outTex;</float4>	// Output texture
<pre>cbuffer RayGenData {</pre>	// World-space camera data
<pre>float3 wsCamPos;</pre>	
<pre>float3 wsCamU, wsCamV,</pre>	wsCamW;
};	
RaytracingAccelerationStruct	ure sceneAccelStruct;

Find pixel center in [0..1] x [0..1] Compute normalized device coordinate (as in raster) Convert NDC into pixel's ray direction (using camera inputs)



RWTexture <float4> outTex;</float4>	// Output texture
<pre>cbuffer RayGenData {</pre>	// World-space camera data
<pre>float3 wsCamPos;</pre>	
<pre>float3 wsCamU, wsCamV,</pre>	wsCamW;
};	
RaytracingAccelerationStruc	<pre>ture sceneAccelStruct;</pre>

Collectively: Turn pixel ID into a ray direction

[shader("raygeneration")]

void PinholeCamera() {

• • •

}

uint2 curPixel = DispatchRaysIndex().xy; uint2 totalPixels = DispatchRaysDimensions().xy; float2 pixelCenter = (curPixel + float2(0.5,0.5)) / totalPixels; float2 ndc = float2(2,-2) * pixelCenter + float2(-1,1); float3 pixelRayDir = ndc.x * wsCamU + ndc.y * wsCamV + wsCamZ;

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RayDesc ray;

. . .

}

ray.Origin = wsCamPos; ray.Direction = normalize(pixelRayDir); ray.TMin = 0.0f; ray.TMax = 1e+38f;

Setup our ray

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RWTexture<float4> outTex; // Output texture
cbuffer RayGenData { // World-space camera data
 float3 wsCamPos;
 float3 wsCamU, wsCamV, wsCamW;
};

RaytracingAccelerationStructure sceneAccelStruct;

[shader("raygeneration")]

void PinholeCamera() {

uint2 curPixel = DispatchRaysIndex().xy; uint2 totalPixels = DispatchRaysDimensions().xy; float2 pixelCenter = (curPixel + float2(0.5,0.5)) / totalPixels; float2 ndc = float2(2,-2) * pixelCenter + float2(-1,1); float3 pixelRayDir = ndc.x * wsCamU + ndc.y * wsCamV + wsCamZ;

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RWTe	xture <float4> outTe</float4>	x; // Output texture	
cbuf	fer RayGenData {	// World-space camera da	It
	<pre>float3 wsCamPos;</pre>		
	<pre>float3 wsCamU, wsC</pre>	amV, wsCamW;	
};			
Rayt	racingAccelerationS	<pre>tructure sceneAccelStruct;</pre>	

RayDesc is a new HLSL built-in type:

<pre>struct RayDesc {</pre>	
<pre>float3 Origin;</pre>	// Where the ray starts
<pre>float TMin;</pre>	<pre>// Min distance for a valid hit</pre>
float3 Direction	on; // Direction the ray goes
<pre>float TMax;</pre>	<pre>// Max distance for a valid hit</pre>
};	

[shader("raygeneration")]

void PinholeCamera() {

uint2 curPixel = DispatchRaysIndex().xy; uint2 totalPixels = DispatchRaysDimensions().xy; float2 pixelCenter = (curPixel + float2(0.5,0.5)) / totalPixels; float2 ndc = float2(2,-2) * pixelCenter + float2(-1,1); float3 pixelRayDir = ndc.x * wsCamU + ndc.y * wsCamV + wsCamZ;

RayDesc ray;

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}

ray.Origin = wsCamPos; ray.Direction = normalize(pixelRayDir); ray.TMin = 0.0f; ray.TMax = 1e+38f;

```
SimpleRayPayload payload = { float3(0, 0, 0) };
```

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RWTexture <float4> outTex;</float4>	// Output texture
<pre>cbuffer RayGenData {</pre>	// World-space camera da ta
<pre>float3 wsCamPos;</pre>	
<pre>float3 wsCamU, wsCamV,</pre>	wsCamW;
};	
RaytracingAccelerationStruc	<pre>ture sceneAccelStruct;</pre>
<pre>struct SimpleRayPaylo</pre>	pad {
<pre>float3 color;</pre>	
};	

Setup our ray's payload

[shader("raygeneration")]

void PinholeCamera() {

```
uint2 curPixel = DispatchRaysIndex().xy;
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float2 ndc = float2(2,-2) * pixelCenter + float2(-1,1);
float3 pixelRayDir = ndc.x * wsCamU + ndc.y * wsCamV + wsCamZ;
```

RayDesc ray;

• • •

```
ray.Origin = wsCamPos;
ray.Direction = normalize( pixelRayDir );
ray.TMin = 0.0f;
ray.TMax = 1e+38f;
```

```
SimpleRayPayload payload = { float3(0, 0, 0) };
```

```
TraceRay( sceneAccelStruct, RAY_FLAG_NONE, 0xFF,
    HIT_GROUP, NUM_HIT_GROUPS, MISS_SHADER,
    ray, payload );
```

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RWTexture <float4> outTex;</float4>	// Output texture
<pre>cbuffer RayGenData {</pre>	// World-space camera dat
<pre>float3 wsCamPos;</pre>	
<pre>float3 wsCamU, wsCamV,</pre>	wsCamW;
};	
RaytracingAccelerationStruct	<pre>ture sceneAccelStruct;</pre>
<pre>struct SimpleRayPayload {</pre>	
<pre>float3 color;</pre>	
};	

Trace our ray

[shader("raygeneration")]

void PinholeCamera() {

```
uint2 curPixel = DispatchRaysIndex().xy;
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float2 pixelCenter = (curPixel + float2(0.5,0.5)) / totalPixels;
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RWTexture<float4> outTex; // Output texture
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};
RaytracingAccelerationStructure sceneAccelStruct;
struct SimpleRayPayload {
 float3 color;
};

A new intrinsic function in HLSL

Can call from ray generation, miss, and closest-hit shaders

= DispatchRaysIndex().xy;

float2 pixelCenter = (curPixel + float2(0.5,0.5)) / totalPixels;

float3 pixelRayDir = ndc.x * wsCamU + ndc.y * wsCamV + wsCamZ;

= float2(2,-2) * pixelCenter + float2(-1,1);

uint2 totalPixels = DispatchRaysDimensions().xy;

[shader("raygeneration")]

void PinholeCamera() {

float2 ndc

. . .

uint2 curPixel

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RWTexture<float4> outTex; // Output texture
cbuffer RayGenData { // World-space camera data
float3 wsCamPos;
float3 wsCamU, wsCamV; wsCamW;
};
RaytracingAccelerationStructure sceneAccelStruct;
struct SimpleRayPayload {
float3 color;

};

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RayDesc ray;
ray.Origin = wsCamPos;
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SimpleRayPayload payload = { float3(0, 0, 0) };
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TraceRay( sceneAccelStruct, RAY_FLAG_NONE, 0xFF,
    HIT_GROUP, NUM_HIT_GROUPS, MISS_SHADER,
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```

Our scene acceleration structure

[shader("raygeneration")]

void PinholeCamera() {

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uint2 curPixel = DispatchRaysIndex().xy;
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GENERATIONS/ VANCOUVER SIGGRAPH2018

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};
RaytracingAccelerationStructure sceneAccelStruct;
struct SimpleRayPayload {
 float3 color;
};

Special traversal behavior for this ray? (Here: No)

[shader("raygeneration")]

void PinholeCamera() {

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uint2 curPixel = DispatchRaysIndex().xy;
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GENERATIONS / VANCOUVER SIGGRAPH2018

RWTexture<float4> outTex; // Output texture
cbuffer RayGenData { // World-space camera data
 float3 wsCamPos;
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};
RaytracingAccelerationStructure sceneAccelStruct;
struct SimpleRayPayload {
 float3 color;
};

Instance mask; $0xFF \rightarrow test all geometry$

This allows us to ignore some geometry via a mask

[shader("raygeneration")]

void PinholeCamera() {

```
uint2 curPixel = DispatchRaysIndex().xy;
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RWTexture<float4> outTex; // Output texture
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};
RaytracingAccelerationStructure sceneAccelStruct;
struct SimpleRayPayload {
 float3 color;
};

Which intersection, any-hit, closest-hit, and miss shaders to use?

Known from C++ API setup & total number of shaders. This case: 0, 1, 0

[shader("raygeneration")]

void PinholeCamera() {

. . .

uint2 curPixel = DispatchRaysIndex().xy; uint2 totalPixels = DispatchRaysDimensions().xy; float2 pixelCenter = (curPixel + float2(0.5,0.5)) / totalPixels; float2 ndc = float2(2,-2) * pixelCenter + float2(-1,1); float3 pixelRayDir = ndc.x * wsCamU + ndc.y * wsCamV + wsCamZ;

RayDesc ray; ray.Origin = wsCamPos; ray.Direction = normalize(pixelRayDir); ray.TMin = 0.0f; ray.TMax = 1e+38f;

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TraceRay( sceneAccelStruct, RAY_FLAG_NONE, 0xFF,
    HIT_GROUP, NUM_HIT_GROUPS, MISS_SHADER,
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 float3 wsCamPos;
 float3 wsCamU, wsCamV, wsCamW;
};
RaytracingAccelerationStructure sceneAccelStruct;
struct SimpleRayPayload {
 float3 color;
};

What ray are we shooting?

[shader("raygeneration")]

void PinholeCamera() {

```
uint2 curPixel = DispatchRaysIndex().xy;
uint2 totalPixels = DispatchRaysDimensions().xy;
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ray.Origin = wsCamPos; ray.Direction = normalize(pixelRayDir); ray.TMin = 0.0f; ray.TMax = 1e+38f;

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GENERATIONS / VANCOUVER SIGGRAPH2018

RWTexture<float4> outTex; // Output texture
cbuffer RayGenData { // World-space camera data
 float3 wsCamPos;
 float3 wsCamU, wsCamV, wsCamW;
};
RaytracingAccelerationStructure sceneAccelStruct;
struct SimpleRayPayload {
 float3 color;
};

What is the ray payload? Stores intermediate, per-ray data

[shader("raygeneration")]

void PinholeCamera() {

```
uint2 curPixel = DispatchRaysIndex().xy;
uint2 totalPixels = DispatchRaysDimensions().xy;
float2 pixelCenter = (curPixel + float2(0.5,0.5)) / totalPixels;
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RayDesc ray;

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ray.Origin = wsCamPos;
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SimpleRayPayload payload = { float3(0, 0, 0) };
```

```
TraceRay( sceneAccelStruct, RAY_FLAG_NONE, 0xFF,
        HIT_GROUP, NUM_HIT_GROUPS, MISS_SHADER,
        ray, payload );
```

```
outTex[curPixel] = float4( payload.color, 1.0f );
```

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RWTexture<float4> outTex; // Output texture
cbuffer RayGenData { // World-space camera data
 float3 wsCamPos;
 float3 wsCamU, wsCamV, wsCamW;
};
RaytracingAccelerationStructure sceneAccelStruct;
struct SimpleRayPayload {
 float3 color;
};

Combine With Simple Ray Type

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```
RWTexture<float4> outTex;
cbuffer RayGenData { float3 wsCamPos, wsCamU, wsCamV, wsCamW; };
RaytracingAccelerationStructure sceneAccelStruct;
struct SimpleRayPayload { float3 color; };
```

[shader("raygeneration")]

```
void PinholeCamera() {
```

```
uint2 curPixel = DispatchRaysIndex().xy;
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float2 ndc = float2(2,-2) * pixelCenter + float2(-1,1);
float3 pixelRayDir = ndc.x * wsCamU + ndc.y * wsCamV + wsCamZ;
```

RayDesc ray;

```
ray.Origin = wsCamPos;
```

```
ray.Direction = normalize( pixelRayDir );
```

```
ray.TMin = 0.0f;
```

```
ray.TMax = 1e+38f;
```

```
SimpleRayPayload payload = { float3(0, 0, 0) };
```

```
outTex[curPixel] = float4( payload.color, 1.0f );
```

```
[shader("miss")]
void RayMiss(inout SimpleRayPayload data)
{
    data.color = float3(0, 0, 1);
}
[shader("closesthit")]
void RayClosestHit(inout SimpleRayPayload data,
        BuiltinIntersectionAttribs attribs)
{
    data.color = float3(1, 0, 0);
}
```

- Now you have a complete DirectX Raytracing shader
 - (Both intersection shader and any-hit shader are optional)
- Shoots rays from app-specified camera
- Returns red if rays hit geometry, blue on background





- All the standard HLSL data types, texture resources, user-definable structures and buffers
 - See <u>Microsoft documentation</u> for more details and course tutorials for more examples



- All the standard HLSL data types, texture resources, user-definable structures and buffers
 - See <u>Microsoft documentation</u> for more details and course tutorials for more examples
- Numerous standard HLSL intrinsic or built-in functions useful for graphics, spatial manipulation, and 3D mathematics
 - Basic math (sqrt, clamp, isinf, log), trigonometry (sin, acos, tanh), vectors (normalize, length), matrices (mul, transpose)
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• All the standard HLSL data types, texture resources, user-definable structures and buffers

- See <u>Microsoft documentation</u> for more details and course tutorials for more examples
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 - Basic math (sqrt, clamp, isinf, log), trigonometry (sin, acos, tanh), vectors (normalize, length), matrices (mul, transpose)
 - See <u>Microsoft documentation</u> for full list and course tutorials for more examples
- New intrinsic functions for ray tracing
 - Functions related to ray traversal: TraceRay(), ReportHit(), IgnoreHit(), and AcceptHitAndEndSearch()
 - Functions for ray state, e.g.: WorldRayOrigin(), RayTCurrent(), InstanceID(), and HitKind()



Ray Traversal Functions	Ray Gen	Intersect	Any Hit	Closest	Miss	Summary
TraceRay()	\checkmark			\checkmark	\checkmark	Launch a new ray
ReportHit()		\checkmark				Found a hit; test it; function returns true if hit accepted
IgnoreHit()			\checkmark			Hit point should be ignored, traversal continues
<pre>AcceptHitAndEndSearch()</pre>			\checkmark			Hit is good; stop search immediately, execute closest hit



Ray Traversal Functions	Ray Gen	Intersect	Any Hit	Closest	Miss	Summary
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<pre>AcceptHitAndEndSearch()</pre>			\checkmark			Hit is good; stop search immediately, execute closest hit

Ray Launch Details	Ray Gen	Intersect	Any Hit	Closest	Miss	Summary
<pre>DispatchRaysDimensions()</pre>	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	How many rays were launched (e.g., 1920 × 1080)
<pre>DispaychRaysIndex()</pre>	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	Why ray (in that range) is the shader currently processing



Ray Traversal Functions	Ray Gen	Intersect	Any Hit	Closest	Miss	Summary
TraceRay()	\checkmark			\checkmark	\checkmark	Launch a new ray
ReportHit()		\checkmark				Found a hit; test it; function returns true if hit accepted
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<pre>AcceptHitAndEndSearch()</pre>			\checkmark			Hit is good; stop search immediately, execute closest hit

Ray Launch Details	Ray Gen	Intersect	Any Hit	Closest	Miss	Summary
<pre>DispatchRaysDimensions()</pre>	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	How many rays were launched (e.g., 1920 × 1080)
<pre>DispaychRaysIndex()</pre>	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	Why ray (in that range) is the shader currently processing

Hit Specific Details	Ray Gen	Intersect	Any Hit	Closest	Miss	Summary
HitKind()			\checkmark	\checkmark		Information about what kind of hit we're processing
						(Developer data specified by your intersection shader. For triangles can be:
						HIT_KIND_TRIANGLE_FRONT_FACE or HIT_KIND_TRIANGLE_BACK_FACE)



Ray Introspection	Ray Gen	Intersect	Any Hit	Closest	Miss	Summary
RayTCurrent()		\checkmark	\checkmark	\checkmark	\checkmark	Current distance along the ray
RayTMin()		\checkmark	\checkmark	\checkmark	\checkmark	Min ray distance, as passed to this ray's TraceRay()
RayFlags()		\checkmark	\checkmark	\checkmark	\checkmark	The flags passed to this ray's TraceRay()
WorldRayOrigin()		\checkmark	\checkmark	\checkmark	\checkmark	The ray origin passed to this ray's TraceRay()
<pre>WorldRayDirection()</pre>		\checkmark	\checkmark	\checkmark	\checkmark	The ray direction passed to this ray's TraceRay()



Current Object Introspection	Ray Gen	Intersect	Any Hit	Closest	Miss	Summary
<pre>InstanceIndex()</pre>		\checkmark	\checkmark	\checkmark		Instance index in acceleration structure (generated)
<pre>InstanceID()</pre>		\checkmark	\checkmark	\checkmark		Instance identifier in acceleration struct (user-provided)
<pre>PrimitiveIndex()</pre>		\checkmark	\checkmark	\checkmark		Index of primitive in geometry instance (generated)
ObjectToWorld()		\checkmark	\checkmark	\checkmark		Matrix to transform object-space to world-space
WorldToObject()		\checkmark	\checkmark	\checkmark		Matrix to transform world-space to object-space
ObjectRayOrigin()		\checkmark	\checkmark	\checkmark		<pre>Essentially: WorldToObject(WorldRayOrigin())</pre>
ObjectRayDirection()		\checkmark	\checkmark	\checkmark		<pre>Essentially: WorldToObject(WorldRayDirection())</pre>